

ArtiMinds Robot Programming Suite (RPS)



PLANNING & SIMULATION

Offline programming with collision-free path planning, setup of safety zones, accessibility analysis and cycle time estimation



PROGRAMMING OF COMPLEX PROGRAM LOGIC

Communication with PLC and other external systems, logical programming beyond simple path planning



CAD2PATH

Automatic generation of surface accurate paths for robots based on CAD data



FORCE & VISION CONTROLLED ROBOT PROGRAMMING

Sensitive processes, handling of non-rigid materials and sensitive parts, handling of process deviations & tolerances



[Example for Force Sensitive Polishing](#)

ArtiMinds Learning & Analytics for Robots (LAR)



VISUALIZATION & ANALYSIS

Process oriented past, present and future analysis, e.g. predictive maintenance, detection of new batches, tool wear and tear, etc.



SELF-OPTIMIZATION

Self-learning methods for optimizing the parameters of the robot program, e.g. for minimizing tolerance compensation, reducing cycle time & teach point optimization



PROCESS MONITORING

Display of standard and process-specific parameters; creation of monitoring systems that observe occurring forces or movements of the robot and that inform you of errors



DATA STORAGE & SYSTEM INTEGRATION

Long-term storage of process data in your own local database; integration into higher-level MES systems



[Data Analytics with ArtiMinds LAR](#)

APPLICATIONS*

Added Value of ArtiMinds

Multitool for flexible & low-cost automation of various applications, e.g.:



Mechanical Assembly



Electronics Assembly



Quality inspection & surface treatment

Seamlessly implementable in software tool chains including digital backend (e.g. Siemens Teamcenter & Process Simulate)



[Strategic Partnership ArtiMinds & Siemens](#)

SUPPORTED HARDWARE*

Force Torque Sensors



Robotiq



Weiss Robotics



OnRobot



ATI

Gripper Systems



Robotiq



Weiss Robotics



Digital Gripper



OnRobot

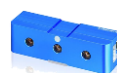


Zimmer

Camera Systems



Cognex



Halcon



SensoPart



Keyence



ifm



SICK

Interfaces

